

MA2007B: LINEAR ALGEBRA I
Midterm2/December 05, 2019

Please show all your work clearly for full credit! each problem 10 points, total 100 points)

- (1) Find the symmetric factorization $A = LDL^T$ of the 3×3 real symmetric matrix

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 2 & 6 \\ 5 & 6 & 3 \end{bmatrix}.$$

Solution: By the elimination, we have

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 2 & 6 \\ 5 & 6 & 3 \end{bmatrix} \xrightarrow{\ell_{21}=4, \ell_{31}=5} \begin{bmatrix} 1 & 4 & 5 \\ 0 & -14 & -14 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{\ell_{32}=1} \begin{bmatrix} 1 & 4 & 5 \\ 0 & -14 & -14 \\ 0 & 0 & -8 \end{bmatrix} = U.$$

Therefore, we obtain the symmetric factorization

$$\begin{aligned} A = LU &= \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 0 & -14 & -14 \\ 0 & 0 & -8 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -14 & 0 \\ 0 & 0 & -8 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = LDL^T. \end{aligned}$$

- (2) Show that if an $n \times n$ real matrix A is invertible, then A^T is also invertible and $(A^T)^{-1} = (A^{-1})^T$.

Proof:

$\because A$ is invertible

$\therefore \exists A^{-1}$ such that $A^{-1}A = I$ and $AA^{-1} = I$

$\therefore (A^{-1}A)^T = I^T = I$ and $(AA^{-1})^T = I^T = I$

$\therefore A^T(A^{-1})^T = I$ and $(A^{-1})^T A^T = I$

$\therefore A^T$ is invertible and $(A^T)^{-1} = (A^{-1})^T$

- (3) Let $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times p}$. Show that $C(A)$ is a subspace of \mathbb{R}^m and $C(AB) \subseteq C(A)$, where $C(M)$ denotes the column space of matrix M .

Proof:

- (i) Let $A = [A_1, A_2, \dots, A_n]$, where $A_i \in \mathbb{R}^m$, $1 \leq i \leq n$, are the column vectors of A . Then the column space of A is given by

$$C(A) = \{c_1A_1 + c_2A_2 + \dots + c_nA_n \mid c_1, c_2, \dots, c_n \in \mathbb{R}\} \subseteq \mathbb{R}^m.$$

Let $v := c_1A_1 + c_2A_2 + \dots + c_nA_n$, $w := d_1A_1 + d_2A_2 + \dots + d_nA_n \in C(A)$ and $c \in \mathbb{R}$. Then

$$\begin{aligned} v + w &= (c_1A_1 + c_2A_2 + \dots + c_nA_n) + (d_1A_1 + d_2A_2 + \dots + d_nA_n) \\ &= (c_1 + d_1)A_1 + (c_2 + d_2)A_2 + \dots + (c_n + d_n)A_n \in C(A), \\ cv &= c(c_1A_1 + c_2A_2 + \dots + c_nA_n) \\ &= cc_1A_1 + cc_2A_2 + \dots + cc_nA_n \in C(A). \end{aligned}$$

Therefore, $C(A)$ is a subspace of \mathbb{R}^m .

- (ii) Let $B = [B_1, B_2, \dots, B_p]$, where $B_i \in \mathbb{R}^n, i = 1, 2, \dots, p$, are the column vectors of B . Then $AB = A[B_1, B_2, \dots, B_p] = [AB_1, AB_2, \dots, AB_p]$, and

$$C(AB) = \text{the set of all linear combinations of } AB_1, AB_2, \dots, AB_p.$$

Let $v \in C(AB)$. Then v is a linear combination of AB_1, AB_2, \dots, AB_p .

\therefore For each i , AB_i is a linear combination of columns of A

$\therefore v$ is a linear combination of columns of A

$\therefore v \in C(A)$

$\therefore C(AB) \subseteq C(A)$

- (4) Let V be a vector space over the field \mathbb{F} and let K be a nonempty subset of V . Define

$$S := \{c_1v_1 + c_2v_2 + \dots + c_Nv_N \mid \forall v_1, v_2, \dots, v_N \in K, c_1, c_2, \dots, c_N \in \mathbb{F}, \text{ and } N \in \mathbb{N}\}.$$

Show that S is a subspace of V and S is the smallest subspace of V that contains K .

Proof:

- (i) Obviously, $S \subseteq V$. Let $v, w \in S$ and $c \in \mathbb{F}$. Then

$$v = c_1v_1 + c_2v_2 + \dots + c_Nv_N \text{ for some } v_1, v_2, \dots, v_N \in K \text{ and } c_1, c_2, \dots, c_N \in \mathbb{F},$$

$$w = d_1w_1 + d_2w_2 + \dots + d_Mw_M \text{ for some } w_1, w_2, \dots, w_M \in K \text{ and } d_1, d_2, \dots, d_M \in \mathbb{F}.$$

We obtain

- $v + w = c_1v_1 + c_2v_2 + \dots + c_Nv_N + d_1w_1 + d_2w_2 + \dots + d_Mw_M$ is a linear combination of vectors in $K \implies v + w \in S$.

- $cv = c(c_1v_1 + c_2v_2 + \dots + c_Nv_N) = cc_1v_1 + cc_2v_2 + \dots + cc_Nv_N$ is a linear combination of vectors in $K \implies cv \in S$.

Therefore, S is a subspace of V .

- (ii) Assume that T is a subspace of V that contains K . We want to show that $S \subseteq T$.

Let $v \in S$. Then $\exists v_1, v_2, \dots, v_N \in K$ and $c_1, c_2, \dots, c_N \in \mathbb{F}$ s.t. $v = c_1v_1 + c_2v_2 + \dots + c_Nv_N$.

$\therefore T$ is a subspace of V and $K \subseteq T$ and v is a linear combination of vectors in K

$\therefore v = c_1v_1 + c_2v_2 + \dots + c_Nv_N \in T$

$\therefore S \subseteq T$

- (5) Let $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times p}$. Show that $\text{rank}(AB) \leq \text{rank}(B)$.

Proof: Let $B = [B_1, B_2, \dots, B_p]$. Then $AB = A[B_1, B_2, \dots, B_p] = [AB_1, AB_2, \dots, AB_p]$.

If the j -th column B_j of B is a linear combination of previous columns of B , i.e.,

$$B_j = c_1B_1 + c_2B_2 + \dots + c_{j-1}B_{j-1}, \text{ for some } c_1, c_2, \dots, c_{j-1} \in \mathbb{R},$$

then we have

- B_j is a free column, i.e., B_j is not a pivot column.
- The j -th column of AB is

$$AB_j = A(c_1B_1 + c_2B_2 + \dots + c_{j-1}B_{j-1}) = c_1AB_1 + c_2AB_2 + \dots + c_{j-1}AB_{j-1}.$$

i.e., the j -th column AB_j of AB is a linear combination of previous columns of AB . Therefore, AB_j is not a pivot column of AB .

We can conclude that

$$\text{rank}(AB) = \text{number of pivot columns of } AB \leq \text{number of pivot columns of } B = \text{rank}(B).$$

(6) Consider the linear system $Ax = b$,

$$A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 4 & 8 & 12 \\ 3 & 6 & 7 & 13 \end{bmatrix}, \quad b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}.$$

Reduce the augmented matrix $[A \ b]$ to $[U \ c]$ so that $Ax = b$ becomes a triangular system $Ux = c$ and find the condition on b_1, b_2, b_3 for $Ax = b$ solvable.

Solution:

$$\begin{aligned} [A \ b] &= \begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 2 & 4 & 8 & 12 & b_2 \\ 3 & 6 & 7 & 13 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 0 & 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 0 & -2 & -2 & b_3 - 3b_1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & b_1 \\ 0 & 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 + b_2 - 5b_1 \end{bmatrix} = [U \ c] \end{aligned}$$

Therefore, the solvability condition of $Ax = b$ is $b_3 + b_2 - 5b_1 = 0$.

(7) Let $b := [0, 6, -6]^T$ in Problem (6). Find the reduced row echelon form $[R \ d]$ and find the complete solution to $Ax = b$.

Solution: First, note that $b_3 + b_2 - 5b_1 = -6 + 6 - 0 = 0$.

$$[U \ c] = \begin{bmatrix} 1 & 2 & 3 & 5 & 0 \\ 0 & 0 & 2 & 2 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & 0 \\ 0 & 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 0 & 2 & -9 \\ 0 & 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = [R \ d]$$

Free columns: 2, 4 free variables: x_2, x_4

Pivot columns: 1, 3 pivot variables: x_1, x_3

Consider $Ax = 0 \Leftrightarrow Rx = 0$.

Set $x_2 = 1, x_4 = 0$: $x_1 = -2$ and $x_3 = 0$.

Set $x_2 = 0, x_4 = 1$: $x_1 = -2$ and $x_3 = -1$.

We have two special solutions to $Ax = 0$:

$$s_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad s_2 = \begin{bmatrix} -2 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

Consider $Ax_p = b \Leftrightarrow Rx_p = d$.

Set $x_2 = 0, x_4 = 0$: $x_1 = -9$ and $x_3 = 3$.

We obtain a particular solution to $Ax_p = b$:

$$x_p = \begin{bmatrix} -9 \\ 0 \\ 3 \\ 0 \end{bmatrix}.$$

Therefore, the complete solution to $Ax = b$ is

$$x = x_p + x_n = \begin{bmatrix} -9 \\ 0 \\ 3 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 0 \\ -1 \\ 1 \end{bmatrix}.$$

- (8) Suppose you know that the 3×4 real matrix A has the vector $s = [2, 3, 1, 0]^T$ as the only special solution to $Ax = 0$. (a) What is the rank of A and the complete solution to $Ax = 0$? (b) What is the exact reduced row echelon form R of A ? (c) How do you know that $Ax = b$ can be solved for all $b \in \mathbb{R}^3$?

Solution:

A has only one free variable x_3 and one free column, the 3rd column.

- (a) $\text{rank}(A) = \text{number of pivot columns} = 4 - 1 = 3$. The complete solution to $Ax = 0$ is

$$x = cs = c \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}.$$

- (b) Since $s = [2, 3, 1, 0]^T$, the exact reduced row echelon form R of A is given by

$$R = \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

- (c) $Ax = b$ can be solved for all $b \in \mathbb{R}^3$ because A and R have full row rank $r = 3$.

- (9) Find the largest possible number of independent vectors among

$$v_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}, v_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}, v_4 = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \end{bmatrix}, v_5 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}, v_6 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}.$$

Solution:

- (i) Claim: v_1, v_2, v_3 are linearly independent.

Let $x_1v_1 + x_2v_2 + x_3v_3 = 0$. Then

$$x_1 \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \implies x_1 = 0, \quad x_2 = 0, \quad x_3 = 0.$$

Therefore, v_1, v_2, v_3 are linearly independent.

- (ii) $v_4 = v_2 - v_1 \implies -v_1 + v_2 - v_4 = 0$

$$v_5 = v_3 - v_1 \implies -v_1 + v_3 - v_5 = 0$$

$$v_6 = v_3 - v_2 \implies -v_2 + v_3 - v_6 = 0$$

By (i) and (ii), 3 is the largest number of independent vectors.

- (10) Show that if an $n \times n$ real matrix A is invertible, then the set of all column vectors of A is linearly independent.

Proof:

Let $A = [A_1, A_2, \dots, A_n]$, where $A_i, 1 \leq i \leq n$, are the column vectors of A .

Assume that $x_1A_1 + x_2A_2 + \dots + x_nA_n = 0$, i.e., $Ax = 0$. Then

$\therefore A$ is invertible, so A^{-1} exists

$$\therefore x = A^{-1}Ax = A^{-1}0 = 0$$

$\therefore A_1, A_2, \dots, A_n$ are linearly independent