數值分析 MA-3021

Syllabus

- 授課老師: 鄭經斅 (Ching-hsiao Arthur Cheng)
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 - Office hour: 星期三 1PM 至 2PM
- 課程網頁:

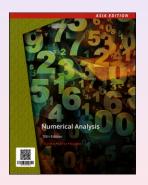
 $http://www.math.ncu.edu.tw/{\sim}cchsiao/Course/Numerical_Analysis_082$

- 助教:蘇逸鎮 / 研究室: M115 / 校分機:65109
- 課程預備知識:微積分、線性代數,以及寫程式的能力(本 課程使用 matlab)
- 作業:原則上每兩週出一次作業,作業請至課程網頁下載。
- 評分方式:作業 40%、期中考 30%、期末考 30%。



Textbook

Richard L. Burden and J. Douglas Faires, Numerical Analysis, 10th Edition, Thomson Brooks/Cole, 2016. (東華書局暨新月書局代理)



Scientific Computing v.s. Numerical Analysis

Problem modelling

- physical phenomena: too expensive to perform all tests with prototypes.
- mathematical model (differential or integral equations): too complex or very difficult for paper/pencil solution.
- computational model (numerical methods): approximation of mathematical model.
- Scientific computing: solving mathematical problems numerically on the computer (methods/constructive proofs → algorithms → codes → display).
- Numerical analysis mathematics of scientific computing: it involves the study, development and analysis of algorithms (procedures) for obtaining numerical solutions to various mathematical problems.

Scientific Computing v.s. Numerical Analysis

Scientific computing: interdisciplinary (跨學科)
science/engineering;
numerical analysis;
computer science;
software engineering.

Topics covered in this course

- Mathematical preliminaries
- Solutions of nonlinear equations
- Interpolation and polynomial approximation
- Numerical differentiation and integration
- Direct and iterative methods for solving linear systems
- Numerical ordinary differential equations*
- Numerical partial differential equations*

Mathematical Preliminaries

- Review of Calculus/Analysis.
- Taylor's Theorem: for functions in single or several variables.
- Rate of convergence: big O notation.

Solutions of nonlinear equations

• Question: given a function $f: \mathbb{R} \to \mathbb{R}$. Find a point $x^* \in \mathbb{R}$ such that

$$f(x^*) = 0.$$

- If f(x) is simple, such as f(x) = 3x + 1 or $f(x) = 3x^2 4x + 1$, then one can use the root formulas. In general, one has to find the root(s) numerically.
- We will study
 - iterative methods for finding the root (bisection method, secant method, Newton type methods);
 - convergence of the methods;
 - extension to systems of nonlinear equations.



Interpolation and polynomial approximation

• Polynomial interpolation (多項式插值)

We are given n+1 data points (x_i, y_i) , $i=0,1,\dots,n$, and we seek a polynomial p such that $p(x_i)=y_i$, $0 \le i \le n$, where $y_i=f(x_i)$ for some function f.

- Hermite interpolation the interpolation of a function and some of its derivatives at a set of nodes. e.g., find a polynomial p such that $p(x_i) = f(x_i)$ and $p'(x_i) = f'(x_i)$, i = 0, 1.
- Spline (樣條) interpolation

A spline function of degree k is a piecewise polynomial of degree at most k having continuous derivatives of all orders up to k-1.



Numerical differentiation and integration

Numerical differentiation

- Based on Taylor's theorem: $f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(\xi)$.
- Based on polynomial interpolation: let p be the Lagrange interpolation of f. Then $f'(x) \approx p'(x)$.
- Numerical integration based on interpolation: let p be the Lagrange interpolation of f. Then $\int_a^b f(x)dx \approx \int_a^b p(x)dx$.
- Gaussian quadrature (高斯積分法): find A_i and x_i , $i=0,1,\cdots,n$, such that $\int_a^b f(x)dx \approx \sum_{i=0}^n A_i f(x_i)$ and it will be exact for polynomials of degree $\leq 2n+1$.

Direct and iterative methods for solving linear systems

Linear system: find the vector $(x_1, x_2)^{\top}$ such that

$$\left[\begin{array}{cc} 1 & 2 \\ 3 & 4 \end{array}\right]_{2\times 2} \left[\begin{array}{c} x_1 \\ x_2 \end{array}\right] = \left[\begin{array}{c} 5 \\ 6 \end{array}\right].$$

The size of the problem is n=2. For small n, the system can be solved by hand, but for large n (could be as large as $n=10^6$), one has to use computers. We will study

- vector, matrix, norm
- Gaussian elimination and matrix factorizations
- iterative methods
- error analysis



Numerical ordinary differential equations

Existence and uniqueness theory of the initial value problem:

$$x'(t) = f(t, x), \quad x(t_0) = x_0.$$

Taylor-series method:

$$x(t+h) = x(t) + hx'(t) + \frac{h^2}{2!}x''(t) + \frac{h^3}{3!}x'''(t) + \cdots$$

- Runge-Kutta methods: in Taylor-series method, we have to determine x'', x''', \cdots . The Runge-Kutta methods avoid this difficulty.
- Multistep methods: e.g., Adams-Bashforth-formula of order 5: $x_{n+1} = x_n + \frac{h}{720} \{1901f_n 2774f_{n-1} + 2616f_{n-2} 1274f_{n-3} + 251f_{n-4}\}.$
- Convergence, stability and consistency: for multistep method,
- Boundary value problems: finite difference methods.



 $convergent \iff stable + consistent.$

Numerical partial differential equations

- Parabolic problems: finite difference method (explicit, implicit)
- Elliptic problems: finite difference & finite element methods
- Hyperbolic problems: characteristics