

## Exercise Problem Sets 15

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**Problem 1.** Let  $U \subseteq \mathbb{R}^n$  be open, and  $f : U \rightarrow \mathbb{R}^m$  with  $f = (f_1, \dots, f_m)$ .

1. Suppose that  $f$  is differentiable on  $U$  and the line segment joining  $x$  and  $y$  lies in  $U$ . Then there exist points  $c_1, \dots, c_m$  on that segment such that

$$f_i(y) - f_i(x) = (Df_i)(c_i)(y - x) \quad \forall i = 1, \dots, m.$$

2. Suppose in addition that  $U$  is convex (the convexity of sets is defined in Problem 7 in Exercise 11). Show that for each  $x, y \in U$  and vector  $v \in \mathbb{R}^m$ , there exists  $c$  on the line segment joining  $x$  and  $y$  such that

$$v \cdot [f(x) - f(y)] = v \cdot (Df)(c)(x - y).$$

In particular, show that if  $\sup_{x \in U} \|(Df)(x)\|_{\mathcal{B}(\mathbb{R}^n, \mathbb{R}^m)} \leq M$ , then

$$\|f(x) - f(y)\|_{\mathbb{R}^m} \leq M \|x - y\|_{\mathbb{R}^n} \quad \forall x, y \in U.$$

*Proof.* Let  $\gamma : [0, 1] \rightarrow \mathbb{R}^n$  be given by  $\gamma(t) = (1 - t)x + ty$ . Then by the chain rule, for each  $i = 1, \dots, m$ ,  $(f_i \circ \gamma) : [0, 1] \rightarrow \mathbb{R}$  is differentiable on  $(0, 1)$ ; thus the mean value theorem (for functions of one real variable) implies that there exists  $t_i \in (0, 1)$  such that

$$f_i(y) - f_i(x) = (f_i \circ \gamma)(1) - (f_i \circ \gamma)(0) = (f_i \circ \gamma)'(t_i) = (Df_i)(c_i)(\gamma'(t_i)),$$

where  $c_i = \gamma(t_i)$ . Part 1 is concluded since  $\gamma'(t_i) = y - x$ .

For  $v \in \mathbb{R}^m$ , let  $g(t) = v \cdot f(ty + (1 - t)x)$ . Then  $g : [0, 1] \rightarrow \mathbb{R}$  is differentiable; thus the mean value theorem (for functions of one real variable) implies that there exists  $0 < t_0 < 1$  such that

$$v \cdot [f(y) - f(x)] = g(1) - g(0) = g'(t_0) = v \cdot (Df)(t_0y + (1 - t_0)x)(x - y).$$

Letting  $c = t_0y + (1 - t_0)x$ , we conclude that  $v \cdot [f(x) - f(y)] = v \cdot (Df)(c)(x - y)$ .

Finally, let  $v = f(y) - f(x)$ . By the discussion above there exists  $c \in \overline{xy}$  such that

$$\|f(y) - f(x)\|_{\mathbb{R}^m}^2 = v \cdot [f(y) - f(x)] = v \cdot (Df)(c)(x - y).$$

The Cauchy-Schwarz inequality further implies that

$$\begin{aligned} \|f(y) - f(x)\|_{\mathbb{R}^m}^2 &\leq \|f(y) - f(x)\|_{\mathbb{R}^m} \|(Df)(c)(x - y)\|_{\mathbb{R}^m} \\ &\leq \|f(y) - f(x)\|_{\mathbb{R}^m} \|(Df)(c)\|_{\mathcal{B}(\mathbb{R}^n, \mathbb{R}^m)} \|x - y\|_{\mathbb{R}^n}. \end{aligned}$$

Therefore, if  $\sup_{x \in U} \|(Df)(x)\|_{\mathcal{B}(\mathbb{R}^n, \mathbb{R}^m)} \leq M$ , we conclude that

$$\|f(y) - f(x)\|_{\mathbb{R}^m} \leq M \|x - y\|_{\mathbb{R}^n} \quad \forall x, y \in U. \quad \square$$

**Problem 2.** Let  $U \subseteq \mathbb{R}^n$  be open and connected, and  $f : U \rightarrow \mathbb{R}$  be a function such that  $\frac{\partial f}{\partial x_j}(x) = 0$  for all  $x \in U$ . Show that  $f$  is constant in  $U$ .

*Proof.* First, we show that if  $B(a, r)$  is a ball in  $U$ , then  $f$  is constant on  $U$ . In fact, by the fact that balls are convex set, Problem 1 implies that

$$|f(y) - f(x)| \leq \sup_{z \in B(a, r)} \|(Df)(z)\|_{\mathcal{B}(\mathbb{R}^n, \mathbb{R})} \|x - y\|_{\mathbb{R}^n} \quad \forall x, y \in B(a, r).$$

Since  $\frac{\partial f}{\partial x_j}(x) = 0$  for all  $x \in B(a, r)$ , we find that  $\|(Df)(z)\|_{\mathcal{B}(\mathbb{R}^n, \mathbb{R})} = 0$  for all  $z \in B(a, r)$ ; thus  $f(y) = f(x)$  for all  $x, y \in B(a, r)$ .

Suppose that  $f = c$  in  $B(a, r)$ . Let  $E = f^{-1}(\{c\})$ . Note that the fact  $\frac{\partial f}{\partial x_j}(x) = 0$  for all  $x \in U$  implies that  $Df$  is continuous on  $U$ ; thus  $f$  is continuously differentiable on  $U$ . In particular,  $f$  is continuous; thus  $f^{-1}(\{c\})$  is closed relative to  $U$ . Suppose that  $f^{-1}(\{c\}) = F \cap U$  for some closed set  $F$  in  $\mathbb{R}^n$ . Next we show that  $U \setminus F = \emptyset$  so that  $f = c$  on  $U$ .

Suppose the contrary that  $U \setminus F \neq \emptyset$ . Let  $E_1 = U \cap F^c$  and  $E_2 = U \cap F$ . Then  $U = E_1 \cup E_2$  and Problem 6 in Exercise 7 shows that

$$E_1 \cap \overline{E_2} \subseteq E_1 \cap \overline{F} = U \cap F^c \cap F = \emptyset.$$

Therefore,  $\overline{E_1} \cap E_2 \neq \emptyset$  for otherwise  $U$  is disconnected by Proposition 3.65 in the lecture note. This implies that there exists  $x \in \overline{E_1} \cap E_2$ ; thus there exists  $\{x_k\}_{k=1}^\infty \subseteq U \setminus F$  such that  $x_k \rightarrow x$  as  $k \rightarrow \infty$ . Since  $x \in U$ , there exists  $\epsilon > 0$  such that  $B(x, \epsilon) \subseteq U$ ; thus the convergence of  $\{x_k\}_{k=1}^\infty$  implies that there exists  $N > 0$  such that  $x_k \in B(x, \epsilon)$  for all  $k \geq N$ . By the discussion above,  $f$  is constant on  $B(x, \epsilon)$ ; thus  $f(x_k) = f(x) = c$  for all  $k \geq N$ , a contradiction to that  $x_k \notin F$ .  $\square$

**Problem 3.** Let  $U \subseteq \mathbb{R}^n$  be open, and for each  $1 \leq i, j \leq n$ ,  $a_{ij} : U \rightarrow \mathbb{R}$  be differentiable functions. Define  $A = [a_{ij}]$  and  $J = \det(A)$ . Show that

$$\frac{\partial J}{\partial x_k} = \text{tr}\left(\text{Adj}(A) \frac{\partial A}{\partial x_k}\right) \quad \forall 1 \leq k \leq n,$$

where for a square matrix  $M = [m_{ij}]$ ,  $\text{tr}(M)$  denotes the trace of  $M$ ,  $\text{Adj}(M)$  denotes the adjoint matrix of  $M$ , and  $\frac{\partial M}{\partial x_k}$  denotes the matrix whose  $(i, j)$ -th entry is given by  $\frac{\partial m_{ij}}{\partial x_k}$ .

**Hint:** Show that

$$\frac{\partial J}{\partial x_k} = \begin{vmatrix} \frac{\partial a_{11}}{\partial x_k} & a_{12} & \cdots & a_{1n} \\ \frac{\partial a_{21}}{\partial x_k} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial a_{n1}}{\partial x_k} & a_{n2} & \cdots & a_{nn} \end{vmatrix} + \begin{vmatrix} a_{11} & \frac{\partial a_{12}}{\partial x_k} & a_{13} & \cdots & a_{1n} \\ a_{21} & \frac{\partial a_{22}}{\partial x_k} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \frac{\partial a_{n2}}{\partial x_k} & a_{n3} & \cdots & a_{nn} \end{vmatrix} + \cdots + \begin{vmatrix} a_{11} & \cdots & a_{(n-1)1} & \frac{\partial a_{1n}}{\partial x_k} \\ a_{21} & \cdots & a_{(n-1)2} & \frac{\partial a_{2n}}{\partial x_k} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1} & \cdots & a_{(n-1)n} & \frac{\partial a_{nn}}{\partial x_k} \end{vmatrix}$$

and rewrite this identity in the form which is asked to prove. You can also show the differentiation formula by applying the chain rule to the composite function  $F \circ g$  of maps  $g : U \rightarrow \mathbb{R}^{n^2}$  and  $F : \mathbb{R}^{n^2} \rightarrow \mathbb{R}$  defined by  $g(x) = (a_{11}(x), a_{12}(x), \dots, a_{nn}(x))$  and  $F(a_{11}, \dots, a_{nn}) = \det([a_{ij}])$ . Check first what  $\frac{\partial F}{\partial a_{ij}}$  is.

*Proof.* Let  $A = [a_{ij}]$  and  $\text{Adj}(A) = [c_{ij}]$ . Then  $\frac{\partial F}{\partial a_{ij}} = c_{ji}$  since the cofactor expansion implies that

$$\det(A) = a_{i1}c_{1i} + a_{i2}c_{2i} + \cdots + a_{in}c_{ni} \quad \text{for each } 1 \leq i \leq n.$$

Therefore, for  $J = \det(A)$ , we have

$$\frac{\partial J}{\partial x_k}(x) = \frac{\partial(F \circ g)}{\partial x_k}(x) = \sum_{i,j=1}^n \frac{\partial F}{\partial a_{ij}}(g(x)) \frac{\partial a_{ij}}{\partial x_k}(x) = \sum_{i,j=1}^n c_{ji}(x) \frac{\partial a_{ij}}{\partial x_k}(x)$$

and the result is concluded from the fact that  $\text{tr}\left(\text{Adj}(A) \frac{\partial A}{\partial x_k}\right) = \sum_{i,j=1}^n c_{ji} \frac{\partial a_{ij}}{\partial x_k}$ .  $\square$

**Problem 4.** 1. If  $f : A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$  and  $g : B \subseteq \mathbb{R}^m \rightarrow \mathbb{R}^\ell$  are twice differentiable and  $f(A) \subseteq B$ , then for  $x_0 \in A$ ,  $u, v \in \mathbb{R}^n$ , show that

$$\begin{aligned} D^2(g \circ f)(x_0)(u, v) \\ = (D^2g)(f(x_0))((Df)(x_0)(u), Df(x_0)(v)) + (Dg)(f(x_0))((D^2f)(x_0)(u, v)). \end{aligned}$$

2. If  $p : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is a linear map plus some constant; that is,  $p(x) = Lx + c$  for some  $L \in \mathcal{B}(\mathbb{R}^n, \mathbb{R}^m)$ , and  $f : A \subseteq \mathbb{R}^m \rightarrow \mathbb{R}^s$  is  $k$ -times differentiable, prove that

$$D^k(f \circ p)(x_0)(u^{(1)}, \dots, u^{(k)}) = (D^k f)(p(x_0))((Dp)(x_0)(u^{(1)}), \dots, (Dp)(x_0)(u^{(k)})).$$

**Problem 5.** Let  $f(x, y)$  be a real-valued function on  $\mathbb{R}^2$ . Suppose that  $f$  is of class  $\mathcal{C}^1$  (that is, all first partial derivatives are continuous on  $\mathbb{R}^2$ ) and  $\frac{\partial^2 f}{\partial x \partial y}$  exists and is continuous. Show that  $\frac{\partial^2 f}{\partial y \partial x}$  exists and  $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ .

**Hint:** Mimic the proof of Clairaut's Theorem.

*Proof.* Let  $(a, b) \in \mathbb{R}^2$ . For real numbers  $h, k \neq 0$ , define  $Q : \mathbb{R}^2 \rightarrow \mathbb{R}$  and  $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}$  by

$$Q(h, k) = \frac{1}{hk} [f(a+h, b+k) - f(a+h, b) - f(a, b+k) + f(a, b)]$$

and

$$\psi(x, y) = f(x+h, y) - f(x, y).$$

Then  $Q(h, k) = \frac{1}{hk} [\psi(a, b+k) - \psi(a, b)]$ . By the mean value theorem (for functions of one real variable),

$$\begin{aligned} Q(h, k) &= \frac{1}{hk} \frac{\partial \psi}{\partial y}(a, b + \theta_1 k) k = \frac{1}{h} \left[ \frac{\partial f}{\partial y}(a+h, b + \theta_1 k) - \frac{\partial f}{\partial y}(a, b + \theta_1 k) \right] \\ &= \frac{1}{h} \frac{\partial^2 f}{\partial x \partial y}(a + \theta_2 h, b + \theta_1 k) h = \frac{\partial^2 f}{\partial x \partial y}(a + \theta_2 h, b + \theta_1 k) \end{aligned}$$

for some function  $\theta_1 = \theta_1(h, k)$  and  $\theta_2 = \theta_2(h, k)$  satisfying  $\theta_1, \theta_2 \in (0, 1)$ . Since  $\frac{\partial^2 f}{\partial x \partial y}$  is continuous, we find that

$$\lim_{(h,k) \rightarrow (0,0)} Q(h, k) = \lim_{(h,k) \rightarrow (0,0)} \frac{\partial^2 f}{\partial x \partial y}(a + \theta_2 h, b + \theta_1 k) = \frac{\partial^2 f}{\partial x \partial y}(a, b).$$

On the other hand, since the limit  $\lim_{(h,k) \rightarrow (0,0)} Q(h,k)$  exists,

$$\begin{aligned} \frac{\partial^2 f}{\partial x \partial y}(a,b) &= \lim_{(h,k) \rightarrow (0,0)} Q(h,k) = \lim_{k \rightarrow 0} \lim_{h \rightarrow 0} Q(h,k) \\ &= \lim_{k \rightarrow 0} \frac{1}{k} \left[ \lim_{h \rightarrow 0} \left( \frac{f(a+h, b+k) - f(a, b+k)}{h} - \frac{f(a+h, b) - f(a, b)}{h} \right) \right] \\ &= \lim_{k \rightarrow 0} \frac{1}{k} \left[ \frac{\partial f}{\partial x}(b+k) - \frac{\partial f}{\partial x}(b) \right]; \end{aligned}$$

thus the limit  $\lim_{k \rightarrow 0} \frac{f_x(a, b+k) - f_x(a, b)}{k}$  exists and equals  $\frac{\partial^2 f}{\partial x \partial y}(a, b)$ . By the definition of partial derivatives,  $\frac{\partial^2 f}{\partial y \partial x}(a, b)$  exists and  $\frac{\partial^2 f}{\partial y \partial x}(a, b) = \frac{\partial^2 f}{\partial x \partial y}(a, b)$ .  $\square$

**Problem 6.** Let  $U \subseteq \mathbb{R}^n$  be open, and  $\psi : U \rightarrow \mathbb{R}^n$  be a function of class  $\mathcal{C}^2$ . Suppose that  $(D\psi)(x) \in \text{GL}(n)$  for all  $x \in \mathbb{R}^n$ , and define  $J = \det([D\psi])$  and  $A = [D\psi]^{-1}$ , where  $[D\psi]$  is the Jacobian matrix of  $\psi$ . Write  $[A] = [a_{ij}]$ .

1. Show that for each  $1 \leq i, j, k \leq n$ ,  $a_{ij} : \mathbb{R}^n \rightarrow \mathbb{R}$  is differentiable, and

$$\frac{\partial a_{ij}}{\partial x_k} = - \sum_{r,s=1}^n a_{ir} \frac{\partial^2 \psi_r}{\partial x_k \partial x_s} a_{sj}.$$

2. Show the Piola identity

$$\sum_{i=1}^n \frac{\partial}{\partial x_i} (J a_{ij})(x) = 0 \quad \forall 1 \leq j \leq n \text{ and } x \in U. \quad (0.1)$$

*Proof.* Note that since  $A = [D\psi]^{-1}$ , we have

$$\sum_{r=1}^n a_{ir} \frac{\partial \psi_r}{\partial x_s} = \sum_{r=1}^n \frac{\partial \psi_i}{\partial x_r} a_{rs} = \delta_{is},$$

where  $\delta_{is}$  is the Kronecker delta.

1. The product rule implies that

$$\sum_{r=1}^n \left( \frac{\partial a_{ir}}{\partial x_k} \frac{\partial \psi_r}{\partial x_s} + a_{ir} \frac{\partial^2 \psi_r}{\partial x_k \partial x_s} \right) = 0;$$

thus

$$\sum_{r=1}^n \frac{\partial a_{ir}}{\partial x_k} \frac{\partial \psi_r}{\partial x_s} = - \sum_{r=1}^n a_{ir} \frac{\partial^2 \psi_r}{\partial x_k \partial x_s}.$$

Therefore,

$$\sum_{s=1}^n a_{sj} \sum_{r=1}^n \frac{\partial a_{ir}}{\partial x_k} \frac{\partial \psi_r}{\partial x_s} = - \sum_{s=1}^n \sum_{r=1}^n a_{ir} \frac{\partial^2 \psi_r}{\partial x_k \partial x_s} a_{sj} = - \sum_{r,s=1}^n a_{ir} \frac{\partial^2 \psi_r}{\partial x_k \partial x_s} a_{sj},$$

and Part 1 follows from the fact that  $\sum_{s=1}^n \frac{\partial \psi_r}{\partial x_s} a_{sj} = \delta_{rj}$  and  $\sum_{r=1}^n \delta_{rj} \frac{\partial a_{ir}}{\partial x_k} = \frac{\partial a_{ij}}{\partial x_k}$ .

2. Note that since  $(D\psi) \in \text{GL}(n)$ , by the property of the adjoint matrix we obtain that

$$JA = \det([D\psi])[D\psi]^{-1} = \text{Adj}([D\psi])$$

which implies that the  $(i, j)$ -entry of  $\text{Adj}([D\psi])$  is  $Ja_{ij}$ . Therefore, using the result in Problem 3 shows that

$$\frac{\partial J}{\partial x_i} = \text{tr}\left(\text{Adj}([D\psi])\frac{\partial [D\psi]}{\partial x_i}\right) = \sum_{r,s=1}^n Ja_{rs} \frac{\partial}{\partial x_i} \frac{\partial \psi_s}{\partial x_r} = \sum_{r,s=1}^n Ja_{rs} \frac{\partial^2 \psi_s}{\partial x_i \partial x_r};$$

thus the product rule implies that

$$\begin{aligned} \sum_{i=1}^n \frac{\partial}{\partial x_i} (Ja_{ij}) &= \sum_{i=1}^n \frac{\partial J}{\partial x_i} a_{ij} + \sum_{i=1}^n J \frac{\partial a_{ij}}{\partial x_i} = \sum_{i,r,s=1}^n Ja_{rs} \frac{\partial^2 \psi_s}{\partial x_i \partial x_r} a_{ij} - \sum_{i,r,s=1}^n Ja_{ir} \frac{\partial^2 \psi_r}{\partial x_i \partial x_s} a_{sj} \\ &= \sum_{i,r,s=1}^n Ja_{rs} \frac{\partial^2 \psi_s}{\partial x_i \partial x_r} a_{ij} - \sum_{i,r,s=1}^n Ja_{rs} \frac{\partial^2 \psi_s}{\partial x_r \partial x_i} a_{ij} \\ &= \sum_{i,r,s=1}^n Ja_{rs} \left( \frac{\partial^2 \psi_s}{\partial x_i \partial x_r} - \frac{\partial^2 \psi_s}{\partial x_r \partial x_i} \right) a_{ij} \end{aligned}$$

and the conclusion follows from Clairaut's Theorem. □