

# 分析導論 II MA2050-\*

## Chapter 10. Applications

§10.1 Application on Signal Processing

§10.2 Application on Partial Differential Equations

## §10.1 Application on Signal Processing

In the study of **signal processing**, the Fourier transform and the inverse Fourier transform are often defined by

$$\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx, \check{f}(x) = \int_{\mathbb{R}^n} f(\xi) e^{2\pi i x \cdot \xi} d\xi \quad \forall f \in L^1(\mathbb{R}^n).$$

For  $T \in \mathcal{S}(\mathbb{R}^n)'$ , the Fourier transform of  $T$  is defined again by

$$\langle \hat{T}, \phi \rangle = \langle T, \hat{\phi} \rangle \quad \forall \phi \in \mathcal{S}(\mathbb{R}^n).$$

We also note that the definitions of the translation, dilation, and reflection of tempered distributions are **independent** of the Fourier transform, and are still defined by

$$\langle \tau_h T, \phi \rangle = \langle T, \tau_{-h} \phi \rangle, \langle d_\lambda T, \phi \rangle = \langle T, \lambda^n d_{\lambda^{-1}} \phi \rangle, \langle \tilde{T}, \phi \rangle = \langle T, \tilde{\phi} \rangle$$

for all  $\phi \in \mathcal{S}(\mathbb{R}^n)$ .

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For  $T \in \mathcal{S}'(\mathbb{R}^n)$ , the Fourier transform of  $T$  is defined again by

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## §10.1 Application on Signal Processing

Concerning the convolution, we consider the  $*$  convolution operator

$$(f * g)(x) = \int_{\mathbb{R}^n} f(y)g(x-y) dy = \int_{\mathbb{R}^n} f(x-y)g(y) dy \quad \forall f, g \in L^1(\mathbb{R}^n).$$

instead of  $\star$  convolution operators (which is  $*$ / $\sqrt{2\pi}^n$ ). **The convolution of  $T$  and  $f \in \mathcal{S}(\mathbb{R}^n)$  is defined by**

$$\langle T * f, \phi \rangle = \langle T, \tilde{f} * \phi \rangle = \langle \tilde{T}, f * \tilde{\phi} \rangle \quad \forall \phi \in \mathcal{S}(\mathbb{R}^n).$$

Then for all  $T \in \mathcal{S}(\mathbb{R}^n)'$ ,

- ①  $\check{\tilde{T}} = \hat{\tilde{T}} = T$ ;
- ②  $\widehat{\tau_h T}(\xi) = \hat{T}(\xi)e^{-2\pi i\xi \cdot h}$ ,  $\widehat{d_\lambda T} = \lambda^n d_{\frac{1}{\lambda}} \hat{T}$ ,  $\hat{\tilde{T}} = \check{T}$ .
- ③  $\widehat{T * f} = \hat{T}\hat{f}$  and  $\widehat{fT} = \hat{f} * \hat{T}$  for all  $f \in \mathcal{S}(\mathbb{R}^n)$ . Moreover, if  $S \in \mathcal{S}(\mathbb{R}^n)'$  has the property that  $S * \phi \in \mathcal{S}(\mathbb{R}^n)$  for all  $\phi \in \mathcal{S}(\mathbb{R}^n)$ , then  $\widehat{T * S} = \hat{T}\hat{S}$  in  $\mathcal{S}(\mathbb{R}^n)'$  for all  $T \in \mathcal{S}(\mathbb{R}^n)'$ .

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- ③  $\widehat{T * f} = \widehat{T} \widehat{f}$  and  $\widehat{f T} = \widehat{f} * \widehat{T}$  for all  $f \in \mathcal{S}(\mathbb{R}^n)$ . Moreover, if  $S \in \mathcal{S}(\mathbb{R}^n)'$  has the property that  $S * \phi \in \mathcal{S}(\mathbb{R}^n)$  for all  $\phi \in \mathcal{S}(\mathbb{R}^n)$ , then  $\widehat{T * S} = \widehat{T} \widehat{S}$  in  $\mathcal{S}(\mathbb{R}^n)'$  for all  $T \in \mathcal{S}(\mathbb{R}^n)'$ .

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Moreover,

①  $\widehat{\delta} = \check{\delta} = 1$  in  $\mathcal{S}(\mathbb{R}^n)'$ , and  $\widehat{\delta}_h(\xi) = \widehat{\tau_h \delta}(\xi) = \widetilde{\delta_{-h}} = \widetilde{\tau_{-h} \delta} = e^{-2\pi i h \cdot \xi}$  in  $\mathcal{S}(\mathbb{R}^n)'$  for all  $h \in \mathbb{R}^n$ .

② By Euler's identity,

$$\widehat{\cos(2\pi\omega x)}(\xi) = \frac{1}{2}(\delta_\omega + \delta_{-\omega}), \quad \widehat{\sin(2\pi\omega x)}(\xi) = \frac{1}{2i}(\delta_\omega - \delta_{-\omega}).$$

③  $\delta * \delta = \delta$ , and  $\delta_a * \delta_b = \delta_{a+b}$  for all  $a, b \in \mathbb{R}^n$ .

④  $\delta * \phi = \phi$  and  $\delta_a * \phi = \tau_a \phi$  for all  $\phi \in \mathcal{S}(\mathbb{R}^n)$ .

⑤ Re-define the rect function  $\Pi : \mathbb{R} \rightarrow \mathbb{R}$  by

$$\Pi(x) = \begin{cases} 1 & \text{if } |x| < 1/2, \\ 0 & \text{if } |x| \geq 1/2. \end{cases}$$

Then  $\widehat{\Pi}(\xi) = \check{\Pi}(\xi) = \text{sinc}(\xi)$ , where **sinc** is the **normalized sinc function**.

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$$\Lambda(x) = \begin{cases} 1 - |x| & \text{if } |x| < 1, \\ 0 & \text{if } |x| \geq 1. \end{cases}$$

Then by the fact that  $\Lambda$  is an even function, if  $\xi \neq 0$ ,

$$\begin{aligned} \hat{\Lambda}(\xi) &= 2 \int_0^1 (1-x) \cos(2\pi x\xi) dx \\ &= 2 \left[ (1-x) \frac{\sin(2\pi x\xi)}{2\pi\xi} \Big|_{x=0}^{x=1} + \int_0^1 \frac{\sin(2\pi x\xi)}{2\pi\xi} dx \right] \\ &= \frac{1 - \cos(2\pi\xi)}{2\pi^2\xi^2} = \frac{\sin^2 \pi\xi}{\pi^2\xi^2}, \end{aligned}$$

while  $\hat{\Lambda}(0) = 1$ . Therefore,  $\hat{\Lambda}(\xi) = \text{sinc}^2(\xi)$ . Using the property of convolution, we have  $\Pi * \Pi = \Lambda$ .

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When a continuous function,  $x(t)$ , is sampled at a constant rate  $F_s$  **samples per second** (以每秒  $F_s$  次均勻取樣), there is always an unlimited number of other continuous functions that fit the same set of samples; however, **only one of them is bandlimited to  $F_s/2$  cycles per second (hertz)**, which means that its Fourier transform,  $\hat{x}(f)$ , is 0 for all  $|f| \geq F_s/2$ .

### Definition

Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be a function.  $f$  is said to be a **bandlimited** function if  $\text{spt}(\hat{f})$  is bounded. The **bandwidth** of a bandlimited function  $f$  is the number  $\sup \text{spt}(\hat{f})$ .  $f$  is said to be **timelimited** if  $\text{spt}(f)$  is bounded.

Recall that **the support of a function is the closure of the set on which the function has non-zero value.**

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### Definition

In signal processing, the **Nyquist rate** is twice the bandwidth of a bandlimited function or a bandlimited channel.

In the field of **digital** signal processing, the **sampling theorem** is a fundamental bridge between continuous-time signals (often called "analog signals") and discrete-time signals (often called "digital signals"). It **establishes a sufficient condition for a sample rate** (取樣頻率) that permits a discrete sequence of samples to capture **all the information** from a continuous-time signal of finite bandwidth. To be more precise, Shannon's version of the theorem states that "if an analog signal contains no frequencies higher than  $B$  hertz, it is completely determined by giving its ordinates at a series of points spaced  $\frac{1}{2B}$  seconds apart."

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In the following, we examine the sampling theorem rigorously. We start with the simplest version that the signal is continuous and integrable.

### Theorem

Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be a continuous integrable function. If  $\text{spt}(\hat{f}) \subseteq [-B, B]$ , then  $f$  is fully determined by the sequence  $\left\{ f\left(\frac{k}{2B}\right) \right\}_{k=-\infty}^{\infty}$ , and

$$f(x) = \sum_{k=-\infty}^{\infty} f\left(\frac{k}{2B}\right) \text{sinc}(2Bx - k) \quad \forall x \in \mathbb{R}. \quad (1)$$

**Remark:** Equation (1) is called the *Whittaker-Shannon interpolation formula*.

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**Remark:** Suppose that  $f \in \mathcal{C}(\mathbb{R}; \mathbb{R})$  be such that  $\hat{f}$ , in the sense of tempered distribution, belongs to  $L^2(\mathbb{R})$  and has support in  $[-B, B]$ . By the definition of the Fourier transform for  $\mathcal{S}(\mathbb{R})'$  we have

$$\langle \check{\hat{f}} - f, \phi \rangle = 0 \quad \forall \phi \in \mathcal{S}(\mathbb{R});$$

thus by the fact that  $\check{\hat{f}} \in \mathcal{C}_b(\mathbb{R}; \mathbb{R})$ ,

$$f(x) = \check{\hat{f}}(x) = \int_{-B}^B \hat{f}(\xi) e^{2\pi i \xi x} d\xi \quad \forall x \in \mathbb{R}.$$

Therefore, the Fourier coefficients of  $\hat{f}$  is again  $\left\{ \frac{1}{2B} f\left(\frac{-k}{2B}\right) \right\}_{k=-\infty}^{\infty}$  so that the same argument of showing Shannon's Sampling Theorem establishes the Whittaker–Shannon interpolation formula.

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**Remark** (Inner product point of view): Let

$$e_k(x) = \text{sinc}(x - k) = (\tau_k \text{sinc})(x).$$

Then  $e_k \in L^2(\mathbb{R})$  since

$$\int_{\mathbb{R}} |e_k(x)|^2 dx = \int_{\mathbb{R}} \text{sinc}^2 x dx = \int_{\mathbb{R}} \frac{\sin^2 \pi x}{\pi^2 x^2} dx = \frac{1}{\pi} \int_{\mathbb{R}} \frac{\sin^2 x}{x^2} dx < \infty.$$

By the Plancherel formula (for  $L^2$ -functions),

$$\begin{aligned} \langle e_k, e_\ell \rangle_{L^2(\mathbb{R})} &= \langle \widehat{\tau_k \text{sinc}}, \widehat{\tau_\ell \text{sinc}} \rangle_{L^2(\mathbb{R})} = \int_{\mathbb{R}} \Pi(\xi) e^{2\pi i k \xi} \overline{\Pi(\xi) e^{2\pi i \ell \xi}} d\xi \\ &= \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{2\pi i(k-\ell)\xi} d\xi \end{aligned}$$

which is 0 if  $k \neq \ell$  and is 1 if  $k = \ell$ . Therefore, we find that  $\{e_k\}_{k \in \mathbb{Z}}$  is an orthonormal set in  $L^2(\mathbb{R})$ .

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Now suppose that  $f \in L^2(\mathbb{R})$  (so that  $\hat{f} \in L^2(\mathbb{R})$  by the Plancherel formula) such that  $\text{spt}(\hat{f}) \subseteq (-1/2, 1/2)$ . Then

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if  $f$  is continuous at  $k$ . By the previous remark, if  $f \in L^2(\mathbb{R}) \cap \mathcal{C}(\mathbb{R})$  such that  $\text{spt}(\hat{f}) \subseteq (-1/2, 1/2)$ , then

$$f(x) = \sum_{k=-\infty}^{\infty} f(k) \text{sinc}(x-k) = \sum_{k=-\infty}^{\infty} \langle f, e_k \rangle_{L^2(\mathbb{R})} e_k(x) \quad \forall x \in \mathbb{R}.$$

In other words, one can treat  $\{e_k\}_{k \in \mathbb{Z}}$  as an “orthonormal basis” in the space

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## §10.1 Application on Signal Processing

## Lemma (Poisson summation formula)

Let the Fourier transform and the inverse Fourier transform be defined by

$$\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx, \check{f}(x) = \int_{\mathbb{R}^n} f(\xi) e^{2\pi i x \cdot \xi} d\xi \quad \forall f \in L^1(\mathbb{R}^n).$$

Then

$$\sum_{n=-\infty}^{\infty} \phi(x+n) = \sum_{k=-\infty}^{\infty} \hat{\phi}(k) e^{2\pi i k x} \quad \forall \phi \in \mathcal{S}(\mathbb{R}).$$

The convergences on both sides are uniform.

**Remark:** Using the original definition of the Fourier transform, for  $\phi \in \mathcal{S}(\mathbb{R})$  one has

$$\sum_{n=-\infty}^{\infty} \phi(x+2n\pi) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} \hat{\phi}(n) e^{inx}.$$

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## §10.1 Application on Signal Processing

The **Shah** function, also called the **(Dirac) Comb** function and is denoted by  $\mathbb{III}$ , is a tempered distribution defined by

$$\langle \mathbb{III}, \phi \rangle = \sum_{n=-\infty}^{\infty} \phi(n) \quad \forall \phi \in \mathcal{S}(\mathbb{R}).$$

We note that the sum above makes sense if  $\phi \in \mathcal{S}(\mathbb{R})$ , and

$$\sum_{n=-\infty}^{\infty} \phi(n) = \sum_{n=-\infty}^{\infty} \langle n \rangle^{-k} \langle n \rangle^k \phi(n) \leq \left( \sum_{n=-\infty}^{\infty} \langle n \rangle^{-k} \right) p_k(\phi) = C_k p_k(\phi)$$

for all  $k \geq 2$ . Therefore,  $\mathbb{III}$  is indeed a tempered distribution. Since

$$\phi(n) = \langle \delta_n, \phi \rangle, \text{ symbolically we also write } \mathbb{III} = \sum_{n=-\infty}^{\infty} \delta_n.$$

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- **Properties of the Shah function:**

- ① By the definition of the Fourier transform of tempered distributions,

$$\langle \widehat{\text{III}}, \phi \rangle = \langle \text{III}, \widehat{\phi} \rangle = \sum_{n=-\infty}^{\infty} \widehat{\phi}(n) \quad \forall \phi \in \mathcal{S}(\mathbb{R}),$$

and the Poisson summation formula implies that

$$\langle \widehat{\text{III}}, \phi \rangle = \sum_{k=-\infty}^{\infty} \phi(k) = \langle \text{III}, \phi \rangle \quad \forall \phi \in \mathcal{S}(\mathbb{R}).$$

Therefore,  $\widehat{\widehat{\text{III}}} = \check{\text{III}} = \text{III}$  in  $\mathcal{S}(\mathbb{R})'$ .

## §10.1 Application on Signal Processing

- ② For  $p \neq 0$ , define  $\mathbb{I}\mathbb{I}_p = \frac{1}{p} d_p \mathbb{I}\mathbb{I}$ , where  $d_p$  is a dilation operator. Then using

$$\langle d_\lambda T, \phi \rangle = \langle T, \lambda^n d_{\lambda^{-1}} \phi \rangle \quad \forall \phi \in \mathcal{S}(\mathbb{R}^n),$$

we find that for  $\phi \in \mathcal{S}(\mathbb{R})$ ,

$$\begin{aligned} \langle \mathbb{I}\mathbb{I}_p, \phi \rangle &= \left\langle \frac{1}{p} d_p \mathbb{I}\mathbb{I}, \phi \right\rangle = \langle \mathbb{I}\mathbb{I}, d_{p^{-1}} \phi \rangle = \sum_{n=-\infty}^{\infty} (d_{p^{-1}} \phi)(n) \\ &= \sum_{n=-\infty}^{\infty} \phi(pn) = \sum_{n=-\infty}^{\infty} \langle \delta_{pn}, \phi \rangle. \end{aligned}$$

In symbol,  $\mathbb{I}\mathbb{I}_p = \sum_{n=-\infty}^{\infty} \delta_{pn}$ . Moreover,

$$\widehat{\mathbb{I}\mathbb{I}_p} = \widetilde{\mathbb{I}\mathbb{I}_p} = d_{p^{-1}} \mathbb{I}\mathbb{I} = \frac{1}{p} \mathbb{I}\mathbb{I}_{\frac{1}{p}}.$$

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## §10.1 Application on Signal Processing

③ For  $f: \mathbb{R} \rightarrow \mathbb{R}$ , let  $f \text{III}_p: \mathcal{S}(\mathbb{R}) \rightarrow \mathbb{C}$  be defined by

$$\langle f \text{III}_p, \phi \rangle = \sum_{n=-\infty}^{\infty} f(pn)\phi(pn) \quad \forall \phi \in \mathcal{S}(\mathbb{R}).$$

Then  $f \text{III}_p \in \mathcal{S}(\mathbb{R})'$  provided that  $\sum_{n=-\infty}^{\infty} \langle n \rangle^{-k} |f(pn)| < \infty$  for some  $k \in \mathbb{N} \cup \{0\}$  since

$$\begin{aligned} |\langle f \text{III}_p, \phi \rangle| &\leq \sum_{n=-\infty}^{\infty} |f(pn)| \langle pn \rangle^{-k} \langle pn \rangle^k |\phi(pn)| \\ &\leq \max\{1, p^{-k}\} \left( \sum_{n=-\infty}^{\infty} \langle n \rangle^{-k} |f(pn)| \right) p_k(\phi). \end{aligned}$$

In particular,  $f \text{III}_p \in \mathcal{S}(\mathbb{R})'$  if  $f \in \mathcal{S}(\mathbb{R})$ . Moreover, we have

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## §10.1 Application on Signal Processing

- ④ Suppose that  $f \text{ III}_p \in \mathcal{S}(\mathbb{R})'$ . If  $\phi, \psi \in \mathcal{S}(\mathbb{R})$ ,

$$\begin{aligned} \langle f \text{ III}_p * \phi, \psi \rangle &= \langle f \text{ III}_p, \tilde{\phi} * \psi \rangle = \sum_{n=-\infty}^{\infty} f(pn) (\tilde{\phi} * \psi)(pn) \\ &= \sum_{n=-\infty}^{\infty} f(pn) \int_{\mathbb{R}} \phi(y-pn) \psi(y) dy \\ &= \sum_{n=-\infty}^{\infty} f(pn) \langle \tau_{pn} \phi, \psi \rangle. \end{aligned}$$

which shows that (in symbol)

$$f \text{ III}_p * \phi = \sum_{n=-\infty}^{\infty} f(pn) \tau_{pn} \phi \quad \forall \phi \in \mathcal{S}(\mathbb{R})$$

whenever  $f \text{ III}_p \in \mathcal{S}(\mathbb{R})'$ .

# §10.1 Application on Signal Processing

## Definition

Let  $T \in \mathcal{S}(\mathbb{R}^n)'$  be a tempered distribution. The support of  $T$ , denoted by  $\text{spt}(T)$ , is the complement of the open set  $O = \bigcup_{U \in \mathcal{F}(T)} U$ , where  $\mathcal{F}(T)$  is a collection of open sets given by

$$\mathcal{F}(T) = \left\{ U \subseteq \mathbb{R}^n \text{ open} \mid \phi \in \mathcal{S}(\mathbb{R}^n) \wedge \text{spt}(\phi) \subseteq U \Rightarrow \langle T, \phi \rangle = 0 \right\}.$$

The definition above implies that if  $U$  is open and  $U \subseteq O = \text{spt}(T)^c$ , then  $U \in \mathcal{F}(T)$  (since if  $U \notin \mathcal{F}(T)$ , then any open set containing  $U$  does not belong to  $\mathcal{F}(T)$  which results in that  $O \cap U = \emptyset$ ); thus  $\text{spt}(T)^c$  is the “largest” open set in  $\mathcal{F}(T)$ . Moreover, the support of a tempered distribution must be closed; thus if  $\text{spt}(\hat{f}) \subseteq (-B, B)$ , there exists  $0 < R < B$  such that  $\text{spt}(\hat{f}) \subseteq [-R, R]$ . In particular, a choice of  $R$  is the supremum of  $\text{spt}(\hat{f})$ , the bandwidth of  $f$ .

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Let  $T \in \mathcal{S}(\mathbb{R}^n)'$  be a tempered distribution. The support of  $T$ , denoted by  $\text{spt}(T)$ , is the complement of the open set  $O = \bigcup_{U \in \mathcal{F}(T)} U$ , where  $\mathcal{F}(T)$  is a collection of open sets given by

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The definition above implies that if  $U$  is open and  $U \subseteq O = \text{spt}(T)^c$ , then  $U \in \mathcal{F}(T)$  (since if  $U \notin \mathcal{F}(T)$ , then any open set containing  $U$  does not belong to  $\mathcal{F}(T)$  which results in that  $O \cap U = \emptyset$ ); thus  $\text{spt}(T)^c$  is the “largest” open set in  $\mathcal{F}(T)$ . Moreover, the support of a tempered distribution must be closed; thus if  $\text{spt}(\hat{f}) \subseteq (-B, B)$ , there exists  $0 < R < B$  such that  $\text{spt}(\hat{f}) \subseteq [-R, R]$ . In particular, a choice of  $R$  is the supremum of  $\text{spt}(\hat{f})$ , the bandwidth of  $f$ .

## §10.1 Application on Signal Processing

## Example

Let  $\omega \in \mathbb{R}^n$ . The support of  $\delta_\omega$ , the delta function at  $\omega$ , is  $\{\omega\}$ . To see this, let  $U$  be an open set in  $\mathbb{R}^n$  and  $\omega \notin U$ . If  $\phi \in \mathcal{S}(\mathbb{R}^n)$  and  $\text{spt}(\phi) \subseteq U$ , then  $\langle \delta_\omega, \phi \rangle = \phi(\omega) = 0$ ; thus every open set  $U$  that does not contain  $x$  belongs to  $\mathcal{F}(\delta_\omega)$ . This implies that  $\bigcup_{U \in \mathcal{F}(\delta_\omega)} U = \mathbb{R}^n \setminus \{\omega\}$ ; thus the support of  $\delta_\omega$  is  $\{\omega\}$ .

## Example

Let  $T \in \mathcal{S}'(\mathbb{R})$  be the tempered distribution  $T = \delta_\omega - \delta_{-\omega}$ , where  $\omega \neq 0$ . Then  $\text{spt}(T) = \{\omega, -\omega\}$ . Since the Fourier transform of the signal  $f(t) = \sin(2\pi\omega t)$  is  $\hat{f}(\xi) = \frac{\delta_\omega - \delta_{-\omega}}{2i}$ , we find that  $\text{spt}(\hat{f}) = \{-\omega, \omega\}$ .

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## §10.1 Application on Signal Processing

## Lemma

Let  $T \in \mathcal{S}(\mathbb{R}^n)'$  and  $\phi \in \mathcal{S}(\mathbb{R}^n)$ . If  $\text{spt}(T) \cap \text{spt}(\phi) = \emptyset$ , then  $\langle T, \phi \rangle = 0$ .

Proof.

Let  $\phi \in \mathcal{S}(\mathbb{R}^n)$  such that  $\text{spt}(T) \cap \text{spt}(\phi) = \emptyset$ , and  $O = \text{spt}(T)^c$ . Then  $\text{spt}(\phi) \subseteq \text{spt}(T)^c = O$ . Since  $O \in \mathcal{F}(T)$ ,  $\langle T, \phi \rangle = 0$ .  $\square$

Theorem (Not known if it is true)

Let  $f \in \mathcal{C}(\mathbb{R}; \mathbb{R}) \cap \mathcal{S}(\mathbb{R})'$ . If  $\text{spt}(\hat{f}) \subseteq (-B, B)$ , then  $f$  is fully determined by the sequence  $\left\{ f\left(\frac{k}{2B}\right) \right\}_{k=-\infty}^{\infty}$ , and

$$f = \sum_{k=-\infty}^{\infty} f\left(\frac{k}{2B}\right) \tau_{\frac{k}{2B}} d_{\frac{1}{2B}} \text{sinc} \quad \text{in } \mathcal{S}(\mathbb{R})'.$$

## §10.1 Application on Signal Processing

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## §10.2 Application on Partial Differential Equations

Recall that in mathematical modelling we talked about the heat equation

$$u_t - \Delta u = f \quad \text{in } \Omega \times (0, T), \quad (2a)$$

$$u = u_0 \quad \text{on } \Omega \times \{t = 0\}, \quad (2b)$$

together with one of the following boundary condition (called (2c)):

- ① **Dirichlet B.C.:**  $u = g$  on  $\partial\Omega$ .
- ② **Neumann B.C.:**  $\frac{\partial u}{\partial \mathbf{N}} = g$  on  $\partial\Omega$ , where  $\frac{\partial u}{\partial \mathbf{N}} = \nabla u \cdot \mathbf{N}$  is the directional derivative of  $u$  in the outward-pointing direction  $\mathbf{N}$ .
- ③ **Robin B.C.:**  $\frac{\partial u}{\partial \mathbf{N}} + u = g$  on  $\partial\Omega$ .
- ④ **Periodic B.C.:**  $u(0, t) = u(L, t)$  for all  $t > 0$ .

Here  $\Omega \subseteq \mathbb{R}^n$  is an open set, and the functions  $f$ ,  $g$  and  $h$  are given.

## §10.2 Application on Partial Differential Equations

### §10.2.1 The case $\Omega = (0, L)$

• **Dirichlet B.C.:** Here the Dirichet boundary condition becomes  $u(0, t) = a(t)$  and  $u(L, t) = b(t)$  for some given functions  $a, b$ .

Let  $v(x, t) = u(x, t) - \frac{b(t) - a(t)}{L}x - a(t)$ . Then  $v$  satisfies

$$v_t - v_{xx} = F \quad \text{in } (0, L) \times (0, T), \quad (3a)$$

$$v = v_0 \quad \text{on } (0, L) \times \{t = 0\}, \quad (3b)$$

$$v = 0 \quad \text{on } \{0, L\} \times (0, T), \quad (3c)$$

where  $F(x, t) = f(x, t) - \frac{b'(t) - a'(t)}{L}x - a'(t)$ , and  $v_0(x) = u_0(x) - \frac{b(0) - a(0)}{L}x - a(0)$ . In other words, W.L.O.G. we can assume that  $a = b = 0$ .



## §10.2 Application on Partial Differential Equations

Now consider

$$\begin{aligned} u_t - u_{xx} &= f && \text{in } (0, L) \times (0, T), \\ u &= u_0 && \text{on } (0, L) \times \{t = 0\}, \\ u &= 0 && \text{on } \{0, L\} \times (0, T). \end{aligned}$$

The idea of solving the PDE above is to express the solution  $u(x, t)$ , for each  $t \in (0, T)$  as a Fourier series. There are three possible choices:

- ①  $u(x, t) = \frac{c_0(t)}{2} + \sum_{k=1}^{\infty} \left[ c_k(t) \cos \frac{2\pi kx}{L} + s_k(t) \sin \frac{2\pi kx}{L} \right]$ .
- ②  $u(x, t) = \frac{c_0(t)}{2} + \sum_{k=1}^{\infty} c_k(t) \cos \frac{\pi kx}{L}$ : the cosine series of  $u$ .
- ③  $u(x, t) = \sum_{k=1}^{\infty} s_k(t) \sin \frac{\pi kx}{L}$ : the sine series of  $u$ .

## §10.2 Application on Partial Differential Equations

Due to the boundary condition, we choose the sine series to represent the solution. We also represent the initial data  $u_0$  and the forcing  $f$  using the sine series

$$u_0(x) = \sum_{k=1}^{\infty} \hat{u}_{0k} \sin \frac{\pi kx}{L}, \quad f(x, t) = \sum_{k=1}^{\infty} f_k(t) \sin \frac{\pi kx}{L},$$

and assume that

$$u_t(x, t) = \sum_{k=1}^{\infty} \frac{\partial}{\partial t} \left[ s_k(t) \sin \frac{\pi kx}{L} \right], \quad u_{xx}(x, t) = \sum_{k=1}^{\infty} \frac{\partial^2}{\partial x^2} \left[ s_k(t) \sin \frac{\pi kx}{L} \right].$$

Then  $\{s_k(t)\}_{k=1}^{\infty}$  satisfies

$$\begin{aligned} \sum_{k=1}^{\infty} \left( s_k'(t) + \frac{\pi^2 k^2}{L^2} s_k(t) \right) \sin \frac{\pi kx}{L} &= \sum_{k=1}^{\infty} f_k(t) \frac{\sin \pi kx}{L}, \\ \sum_{k=1}^{\infty} s_k(0) \sin \frac{\pi kx}{L} &= \sum_{k=1}^{\infty} \hat{u}_{0k} \sin \frac{\pi kx}{L}. \end{aligned}$$

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## §10.2 Application on Partial Differential Equations

Therefore, for each  $k \in \mathbb{N}$  the function  $s_k(t)$  satisfies the IVP

$$s'_k(t) + \frac{\pi^2 k^2}{L^2} s_k(t) = f_k(t), \quad s_k(0) = \hat{u}_{0k}.$$

Method of **Integrating factor**:

Multiplying both sides by  $Q_k(t) \equiv \exp\left(\frac{\pi^2 k^2 t}{L^2}\right)$ ,

$$\frac{d}{dt} [Q_k(t) s_k(t)] = Q_k(t) f_k(t);$$

thus

$$Q_k(t) s_k(t) - s_k(0) = \int_0^t Q_k(s) f_k(s) ds.$$

Therefore, we expect that the solution is given by

$$u(x, t) = \sum_{k=1}^{\infty} \left[ e^{-\frac{\pi^2 k^2 t}{L^2}} \hat{u}_{0k} + \int_0^t e^{\frac{\pi^2 k^2 (s-t)}{L^2}} f_k(s) ds \right] \sin \frac{\pi kx}{L}.$$

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## §10.2 Application on Partial Differential Equations

- **Neumann B.C.:** Here the Neumann boundary condition becomes  $u_x(0, t) = a(t)$  and  $u_x(L, t) = b(t)$  for some given functions  $a, b$ .

Let  $v(x, t) = u(x, t) - \frac{b(t) - a(t)L}{2L}x^2 - a(t)x$ . Then  $v$  satisfies

$$v_t - v_{xx} = F \quad \text{in } (0, L) \times (0, T), \quad (4a)$$

$$v = v_0 \quad \text{on } (0, L) \times \{t = 0\}, \quad (4b)$$

$$v_x = 0 \quad \text{on } \{0, L\} \times (0, T), \quad (4c)$$

where  $F(x, t) = f(x, t) + \frac{b(t) - a(t)L}{L} - a'(t)x$ , and  $v_0(x) = u_0(x) - \frac{b(0) - a(0)L}{2L}x^2 - a(0)x$ . In other words, W.L.O.G. we can assume that  $a = b = 0$ .

## §10.2 Application on Partial Differential Equations

Due to the boundary condition, we choose the cosine series to represent the solution:

$$u(x, t) = \frac{c_0(t)}{2} + \sum_{k=1}^{\infty} c_k(t) \cos \frac{\pi kx}{L}.$$

We also represent the initial data  $u_0$  and the forcing  $f$  using the sine series

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## §10.2 Application on Partial Differential Equations

Then  $\{c_k(t)\}_{k=0}^{\infty}$  satisfies

$$\frac{c_0'(t)}{2} + \sum_{k=1}^{\infty} \left( c_k'(t) + \frac{\pi^2 k^2}{L^2} c_k(t) \right) \cos \frac{\pi kx}{L} = \frac{f_0(t)}{2} + \sum_{k=1}^{\infty} f_k(t) \frac{\cos \pi kx}{L},$$

$$\frac{c_0(0)}{2} + \sum_{k=1}^{\infty} c_k(0) \cos \frac{\pi kx}{L} = \frac{\hat{u}_{00}}{2} + \sum_{k=1}^{\infty} \hat{u}_{0k} \cos \frac{\pi kx}{L}.$$

The comparison of coefficients shows that  $c_k$  satisfies the IVP

$$c_0'(t) = f_0(t), \quad c_0(0) = \hat{u}_{00}$$

$$c_k'(t) + \frac{\pi^2 k^2}{L^2} c_k(t) = f_k(t), \quad c_k(0) = \hat{u}_{0k}.$$

and are given by

$$c_0(t) = \hat{u}_{00} + \int_0^t f_0(s) ds, \quad c_k(t) = e^{-\frac{\pi^2 k^2 t}{L^2}} \hat{u}_{0k} + \int_0^t e^{-\frac{\pi^2 k^2 (s-t)}{L^2}} f_k(s) ds.$$

## §10.2 Application on Partial Differential Equations

Then  $\{c_k(t)\}_{k=0}^{\infty}$  satisfies

$$\frac{c_0'(t)}{2} + \sum_{k=1}^{\infty} \left( c_k'(t) + \frac{\pi^2 k^2}{L^2} c_k(t) \right) \cos \frac{\pi kx}{L} = \frac{f_0(t)}{2} + \sum_{k=1}^{\infty} f_k(t) \frac{\cos \pi kx}{L},$$

$$\frac{c_0(0)}{2} + \sum_{k=1}^{\infty} c_k(0) \cos \frac{\pi kx}{L} = \frac{\hat{u}_{00}}{2} + \sum_{k=1}^{\infty} \hat{u}_{0k} \cos \frac{\pi kx}{L}.$$

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## §10.2 Application on Partial Differential Equations

Therefore, the solution to

$$\begin{aligned} u_t - u_{xx} &= f && \text{in } (0, L) \times (0, T), \\ u &= u_0 && \text{on } (0, L) \times \{t = 0\}, \\ u_x &= 0 && \text{on } \{0, L\} \times (0, T), \end{aligned}$$

is

$$\begin{aligned} u(x, t) &= \frac{1}{2} \left[ \hat{u}_{00} + \int_0^t f_0(s) ds \right] \\ &+ \sum_{k=1}^{\infty} \left[ e^{-\frac{\pi^2 k^2 t}{L^2}} \hat{u}_{0k} + \int_0^t e^{\frac{\pi^2 k^2 (s-t)}{L^2}} f_k(s) ds \right] \cos \frac{\pi kx}{L}. \end{aligned}$$